

# A11V(L) O Series Axial piston variable pump

#### Product show and brief introduction

#### open circuits

Series 1 Sizes 40 to 260 Nominal pressure 35MPa Maxmum pressure 40MPa



#### Features

- Variable axial piston pump of swashplate design for hydrostatic drives in open circuit hydraulic system.
- Designed primarily for use in mobile applications.
- The pump operates under self-priming conditions, with tank pressurization, or with an optional built-in charge pump (impeller).
- A comprehensive range of control options is available matching any application requirement.
- Power control option is externally adjustable, even when the pump is running.
- The through drive is suitable for adding gear pumps and axial piston pumps up to the same,i.e.100% through drive.
- The output flow is proportional to the drive speed and infinitely variable between q<sub>vmax</sub> and q<sub>vmin</sub>=0



#### Model Code

A11V	L	0	145	LRDS	/10	R	-N	z	D	12	N00
Axial piston unit	Charge pump	Operation	Size	Control unit	series	Driection of rotation	Seals	Drive shaft	Mounting flange	Service line ports	Through drive
A11V: swashplate design, variable	No code: without charge pump L: with charge pump (only 130, 145,190)	O: pump, open circuit	40 60 75 95 115 130 145 190 260	See below	10:size 40 to 115	R:	NBR(nitrile- caoutchouc), shaft seal ring in FKM (fluor- caoutchouc)	See	C: SAE J744 -2 hole (only Ng60) D: SAE J744 -4 hole	Pressure and suction port SAE, at side, opposite side(with metric fastening threads)	See below

#### Control unit

									and the same of			
	Size		40	60	75	95	115	130	145	190	260	
stroke limiter ——		U=12V	V	V	V	V	V	V	V	V	V	LRDU
		U=24V	V	V	V	V	V	V	V	V	V	LRDU
stroke limiter —		∆p=25bar	1	1	0	0	0	0	0	V	V	LRDF
		p=10bar	1	1	V	1	V	1	√	f	1	LRDF
Power control/pressure cut-off/load sensing			V	V	V	V	V	V	V	√	V	LRD
power control, Negative with electronic unauthorized		U=12V	1	1	1	V	V	V	V	V	V	LE1
load sensing	eu	U=24V	1	7	1	V	V	V	V	V	V	LE2
	Electric,prop.override	e U=24V	1	1	1	V	V	V	V	V	V	LE2S
Pressure control with load	sensing	4	1	1	V	V	V	V	V	V	V	DRS
Electric control with proportional solenoid	Positive characteristic	U=12V	1	1	0	V	V	V	V	V	V	EP1
with proportional solenoid		U=24V	1	1	0	V	V	V	V	V	V	EP2
	With pressure cut-off	U=12V	V	V	0	V	V	V	V	V	V	EP1
	positive characteristic	U=24V	V	V	0	V	V	V	V	V	V	EP2I

## Drive shafts

Size			60	75	95	115	130	145	190	260	
Splined shaft DIN5480 for single and	V	V	V	V	<b>√</b>	V	V	V	✓	Z	
Parallel keyed shaft DIN6885			~	V	V	V	V	V	V	V	Р
Splined shaft ANSI B92.1a-1976	for single pump	V	<b>√</b>	V	V	V	V	V	V	V	s
	for combination pump	V	V	V	V	V	/10	/1)	V	V	Т



# Through Drives

Flange SAE J744	Coup	oler for splined sh	aft	40	60	75	95	115	130	145	190	260	
Withiout through drive				✓	/ /	✓	V	√	√	V	V	V	NOC
82-2(A)	5/8"	9T 16/32DP	(A)	$\checkmark$	V	~	<b>√</b>	V	<b>√</b>	V	~	V	K01
	3/4"	11T 16/32DP	(A-B)	$\checkmark$	~	~	~	√	<b>√</b>	√	V	~	K52
101-2(B)	7/8"	13T 16/32DP	(B)	V	V	√	V	√	~	V	V	V	K02
	1"	15T 16/32DP	(B-B)	V	<b>√</b>	<b>√</b>	V	V	~	~	~	V	K04
	W35	2x30x16-9g		$\checkmark$	V	V	<b>√</b>	V	V	V	~	1	K79
127-2(C)	1 1/4"	14T 12/24DP	(C)	/	V	V	V	V	~	V	V	V	K07
	1 1/2"	17T 12/24DP	(C-C)	1	1	1	<b>V</b>	~	~	~	V	- V	K24
	W30	2x30x14-9g		1	<b>√</b>	~	~	~	~	V	V	V	K80
	W35	2x30x16-9g		1	~	~	~	~	V	~	~	V	K6
152-4(D)	1 1/4"	14T 12/24DP	(C)	1	1	<b>√</b>	V	V	~	~	V	V	K86
	1 3/4"	13T 8/16DP	(D)	1	1	1	1	1	1	V	V	V	K17
	W40	2x30x18-9g		1	1	V	V	V	7	V	V	V	K81
	W45	2x30x21-9g		1	1	1	~	V	V	V	~	~	K82
	W50	2x30x24-9g	T	1	1	1	1	1	V	V	~	√	K83
165-4(E)	1 3/4"	13T 8/16DP	(D)	1	1-	1	/	1	1	1	V	V	K72
	W50	2x30x24-9g		1	1	1	1	1	1	1	~	√	K84

 $\sqrt{\ }$  = available / = not available

1) S-shaft suitable combination pump.





#### Technical Data

#### Hydraulic fluid

The A11V(L)O variable displacement pump is suitable for use with mineral oil

#### Viscosity range

For optimum efficiency and service life.select an operating viscosity (at operating temperature) within the optimum range of

V<sub>opt</sub> = optimum viscosity16...36mm<sup>2</sup>/s

depending on the tank temperature (open circuit).

#### Limits of viscosity range

The limiting values for viscosity are as follows:

 $Vmin = 5 mm^2/s$ 

short-term(t < 3 min)

At max.perm. temperature of tmax=+115℃

 $Vmax = 1600 \, mm^2/s$ 

short-term(t < 3 min)

At cold start(P < 3MPa,n ≤ 1000rpm tmin=-40°C).

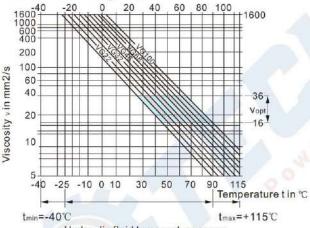
Only for starting up without load. Optimum operating

viscostity must be reached within approx.15 minutes.

Note that the maximun hydraulic fluid temperature of 115°C must not be exceeded locally either (e.g. bearing area). The temperature in the bearing area is-depending on pressure and speed-up to 5 K higher than the average case drain temperature.

Special measures are necessary in the temperature range from -40  $^{\circ}$ C and -25 $^{\circ}$ C (cold start phase), please contact us.

#### Setlection diagram



Hydraulic fluid temperature range

#### Details regarding the choice of hydraulic fluid

The correct selection of hydraulic fluid requires knowledge of the operating temperature in relation to the ambient temperature, in an open circuit the tank temperature.

The hydraulic fliuid should be selected so that within the operating temperature range, the operating viscosity lies within the optimun range ( $V_{\rm opt}$ )(see shaded section of the selection diagram). We recommend that the highest possible viscosity range should be chosen in each case.

Example:At an ambient temperature of X°C an operating temperature of 60°C is set in the circuit. In the optimun operating viscosity range(Vopt; shaded area) this corresponds to the viscosity classes VG 46 or VG68; to be selected: VG 68.

Please note: The leakage fluid temperature, which is affected by pressure and rotational spaad, is always higher than the tank temperature. At no point in the system may the temperature be higher than 115°C.

If the above conditions cannot be maintained due to extreme operating parameters, please contact us.

#### Filtartion

The finer the filtration, the higher the cleanliness level of the hydraulic fluid and the longer the service life of the axial piston unit.

To ensure functional reliability of the axial piston unit, the hydraulic fluid must have a cleanliness level of at least

20/18/15 according to ISO 4406.

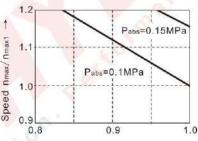
At very high hydraulic fluid temperatures (90 $^{\circ}$  to max.115 $^{\circ}$ ), at least cleanliness level

19/17/14 according to ISO 4406 is required.

If the above classes cannot be observed, please contact us.

#### Maximum permissible speed(speed limit)

Permissible speed by increasing the inlet pressure pabs at the suction port S or at V<sub>g</sub>≤V<sub>gmax</sub>



Displacement Vg/Vgmax →

#### Operating pressure range-Inlet

Absolute pressure at port S (suction port)

Version without charge pump

 Pabs min
 0.08MPa

 Pabs max
 0.3MPa

If the pressure is > 0.5MPa, please ask.

Version with charge pump

 Pabs min
 0.06MPa

 Pabs max
 0.2MPa

#### Operating pressure range-oulet

Pressure at port A or B

 Nominal pressure Pn
 35MPa

 Maximum pressure Pmax
 40MPa

#### Case drain pressure

The case drain pressure at the ports  $T_1$  and  $T_2$  may be a maximum of 0.12MPa higher than the inlet pressure at the port S but not higher than

PLabs.max \_\_\_\_\_\_0.2MPa

An unrestricted, full size case drian line directly to tank is required.



#### Technical Data

#### Table of values (theoretical values, without efficiency and tolerances; values rounded)

Size A11VO			40	60	75	95	115	130	145				
A11VLO(with charg	ge pump)									130	145	190	260
Displacement	V <sub>g max</sub>	mL/r	42	58.5	74	93.5	115	130	145	130	145	193	260
	$V_{gmin}$	mL/r	0	0	0	0	0	0	0	0	0	0	0
Speed													
maximum at Vg max 1)	nmax	rpm	3000	2700	2550	2350	2350	2100	2200	2500	2500	2500	2300
maximum at Vg≤Vg max 3)	Nmax1	rpm	3500	3250	3000	2780	2780	2500	2500	2500	2500	2500	2300
Flow at nmax and Vg max	qv max	L/min	126	158	189	220	270	273	319	325	363	483	598
Power at $q_{v max}$ and $\triangle P=35MPa$	Pmax	kW	74	92	110	128	158	159	186	190	211	281	349
Torque at V <sub>g max</sub> and △P=35MPa	Tmax	Nm	234	326	412	521	641	724	808	724	808	1075	1448
Moment of inertia for rotary gr	oup J	Kgm <sup>2</sup>	0.0048	0.0082	0.0115	0.0173	0.0173	0.0318	0.0341	0.0337	0.036	0.0577	0.0895
Filling capacity	V	L	1.1	1.35	1.85	2.1	2.1	2.9	2.9	2.9	2.9	3.8	4,6
Weight(approx.)	V	kg	32	40	45	53	53	76	76	72	73	104	138

<sup>1)</sup> The values apply at absolute pressure (Pabs) 0.1MPa at the suction port S and mineral hydraulic fluid.

#### Determining the nominal value

Flow 
$$q_v = \frac{V_g \times n \times \eta_v}{1000}$$
 (L/min)

Torque 
$$T = \frac{V_g \times \triangle P}{20 \times \pi \times \eta_{mh}}$$
 (Nm)

Power 
$$P = \frac{2\pi \times T \times n}{60000} = \frac{q_v \times \triangle P}{600 \times \eta_t}$$
 (kW)

V<sub>g</sub> = Displacement per revolution in mL/r

△P = Differential pressure in bar

n = Speed in rpm

ην = Volumetric efficiency

η<sub>mh</sub> = Mechanical-hydraulic efficiency

 $\eta_t = \text{Overall efficiency}(\eta_t = \eta_v. \eta_{mh})$ 

<sup>2)</sup> The values apply at V<sub>g</sub> < V<sub>g max</sub> or in case of an increase in the inlet pressure P<sub>abs</sub> at the suction port S.



The power control regulates the displacement of the pump depending on the operating pressure so that a given drive power is not exceeded at constant drive speed.

P<sub>B</sub>×V<sub>g</sub>=constant

P<sub>B</sub>=operating pressure V<sub>g</sub>=displacement

The precise control with a hyperbolic control characteristic. provides an optimum utilization of available power.

The operating pressure acts on a rocker via a measuring piston. An externally adjustable spring force counteracts this, it determines the power setting.

If the operating pressure exceeds the set spring force, the control valve is actuated by the rocker, the pump swivels back(direction  $V_{g\,min}$ ). The lever length at the rocker is shortened and the operating pressure can increase at the same rate as the displacement decreases without the drive powers being exceeded( $P_B \times V_g = constant$ ).

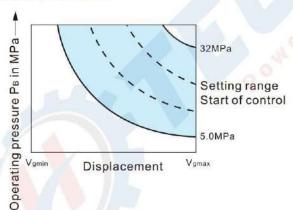
The hydraulic output power(characteristic LR) is influenced by the efficiency of the pump.

State in clear text in the order:

- drive power P in kW
- drive speed n in prm
- max.flow qv max in L/min

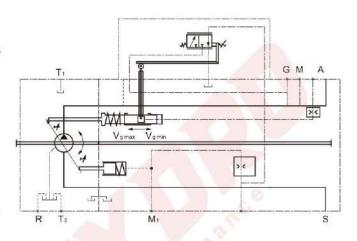
After clarifying the details a power diagram can be created by our computer.

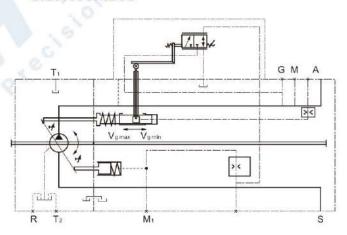
#### Characteristic LR



#### Circuit diagram LR

Size:40...145







#### LE1/2 Electric override (negative)

Contrary to hydraulic power control override, the basic power setting is reduced by an electric pilot current applied to a proportional solenoid. The resulting force is acting against the mechanical power control adjustment spring.

The mechanically adjusted basic power setting can be varied by means of different control current settings.

Increase in current = decrease in power

If the pilot current signal is adjusted by a load limiting control the power consumption of all actuators will be reduced to match the available power from the diesel engine.

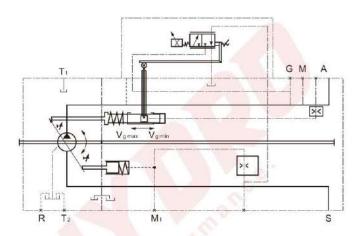
A 12V(LE1) or 24V(LE2) supply is required for the control of the proportion solenoid.

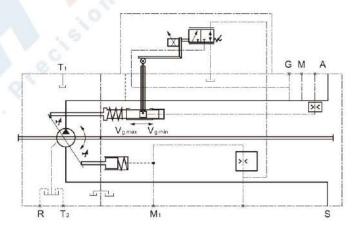
#### Technical data - solenoids

	LE1	LE2
Voltage	12V DC (±20%)	24V DC (±20%)
Control current		
Start of control	400mA	200mA
End of control	1200mA	600mA
Limiting current	1.54A	0.77A
Nominal resistance(at 20°C)	5.5Ω	22.7Ω
Dither frequency	100Hz	100Hz
Actuated time	100%	100%
Type of protection	IP	65

#### Circuit diagram LE1/2

Size:40...145







#### LRD Power control with pressure cut-off

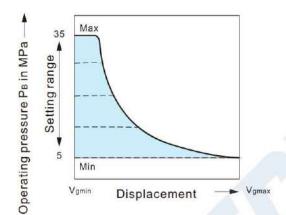
The pressure cut-off corresponds to a pressure control which adjusts the pump displacement back to  $V_{g\,min}$ , when the pressure setting is reached.

This function overrides the power control, i.e. below the preset pressure value, the power function is effective.

The pressure cut-off function is integrated into the pump control module and is preset to a specified value at the factory.

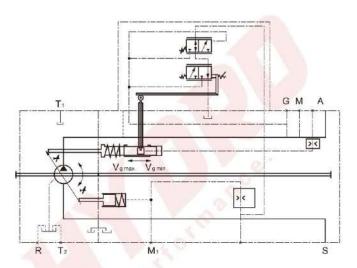
Setting range from 5 to 35 Mpa.

#### Characteristic LRD



#### Circuit diagram LRD

Size:40...145







#### LRDS Power control with pressure cut-off and load sensing

The load sensing control is a flow control option that operates as a function of the load pressure to regulate the pump displacement to match the actuator flow requirement.

The flow depends here on the cross section of the external sensing orifice(1) fitted between the pump outlet and the actuator. The flow is independent of the load pressure below the power curve and the pressure cut-off setting and within the control range of the pump.

The sensing orifice is usually a separately arranged load sensing directional valve (control block). The position of the directional valve piston determines the opening cross section of the sensing orifice and thus the flow of the pump.

The load sensing control compares pressure before and after the sensing orifice and maintains the pressure drop across the orifice (differential pressure  $\triangle P$ ) and with it the pump flow constant.

If the differential pressure  $\triangle P$  increases at the sensing orifice, the pump is swivelled back (towards  $V_{g\,min}$ ), and, if the differential pressure  $\triangle P$  decreases, the pump is swivelled out (towards  $V_{g\,max}$ ) until the pressure drop across the sensing orifice in the valve is restored.

△Porifice = Ppump-Pactuator

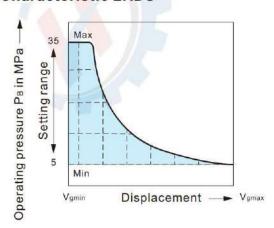
The setting range for △P is between 1.4 MPa and 2.5 MPa.

The standard differential pressure setting is 1.8 MPa.( Please state in clear text when ordering).

The stand-by pressure in zero stroke operation (sensing orifice plugged) is slightly above the  $\triangle P$  setting.

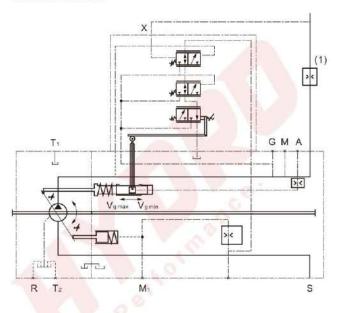
(1) The sensing orifice (control block) is not included in the pump supply.

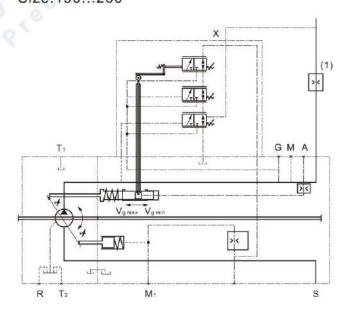
#### Characteristic LRDS



#### Circuit diagram LRDS

Size:40...145







#### LRS2 Power control with load sensing, electric override

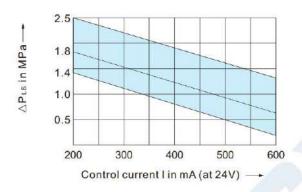
This control option adds a proportional solenoid to override to the mechanically set load sensing pressure. The pressure differential change is proportional to the solenoid current.

Increasing current = smallar △P-setting

See following characteristic for details (example). Please consult us during the project planning phase.

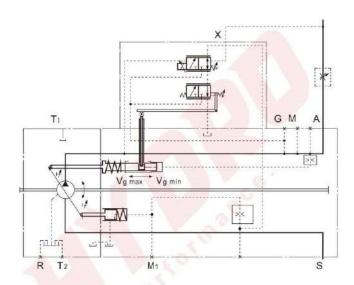
For solenoid specification, see LE2 control

#### Characteristic LRS2

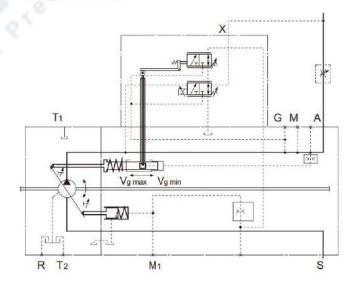


#### Circuit diagram LRS2

Size:40...145



Size:190...260





#### LR... Power control with stroke limiter

The stroke limiter can be used to vary or limit the displacement of the pump continuously over the whole control range. The displacement is set in LRH with the pilot pressure  $P_{st}$  (max.4 Mpa) applied to port Y or in LRU by the control current applied to the proportional solenoid. A DC current of 12V (U1) or 24V(U2) is required to control the proportional solenoid.

The power control overrides the stoke limiter control,i.e. below the hyperbolic power characteristic,the displacement is controlled by the control current or pilot pressure. When exceeding the power characteristic with a set flow or load pressure, the power control overrides and reduces the displacement following the hyperbolic characteristic.

To permit operation of the pump displacement control from its starting position  $V_{g\,max}$  to  $V_{g\,min}$ , a minimum control pressure of 3 MPa is required for the electric stroke limiter LRU1/2 and the hydraulic stroke limiter LRH2/6.

The required control pressure is taken either from the load pressure, or from the externally applied control pressure at the G port.

To ensure functioning of the stroke limiter even at low operating pressure, port G must be supplied with external control pressure of approx.3 Mpa.

Note: If no external control pressure is connected at G, the shuttle valve must be removed.

#### LRH2/6 Hydraulic stroke limiter (positive characteristic)

Control from Vg min to Vg max

With increasing pilot pressure the pump swivels to a higher displacement.

Start of control (at Vg min), can be set \_\_\_\_ from 0.4-1MPa.

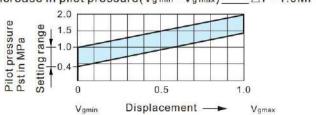
State start of control in clear text in the order.

Starting position without control signal(pilot pressure):

- at operating pressure and external control pressure
   3 MPa: Vg max
- at operating pressure or external control pressure > 3 MPa;Vg min

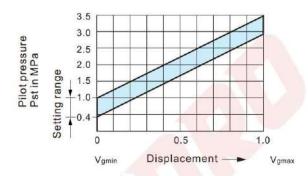
#### Characteristic H6

Increase in pilot pressure( $V_{g \, min}$  -  $V_{g \, max}$ )\_\_\_\_ $\triangle P=1.0 MPa$ 

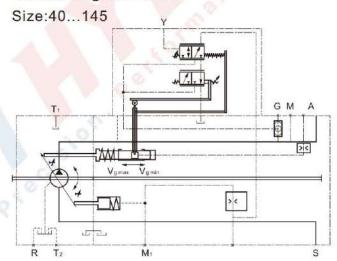


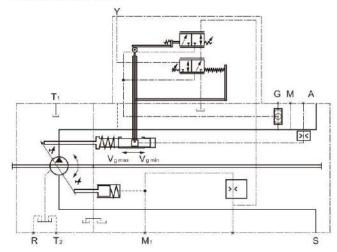
#### Characteristic H2

Increase in pilot pressure(Vg min - Vg max) \_\_\_\_ \( \triangle P = 2.5 MPa



#### Circuit diagram LRS2







#### LRU1/2 Electric stroke limiter (positive characteristic)

Control from Vg min to Vg max

With increasing control current the pump swivels to a higher displacement.

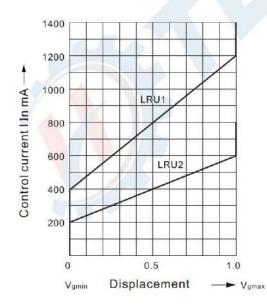
#### Technical data - solenoids

	LRU1	LRU2
Voltage	12V DC (±20%)	24V DC (±20%)
Control current		
Start of control	400mA	200mA
End of control	1200mA	600mA
Limiting current	1.54A	0.77A
Nominal resistance(at 20°C)	5.5Ω	22.7Ω
Dither frequency	100Hz	100Hz
Actuated time	100%	100%
Type of protection	IP65	

Starting position without control signal (control current):

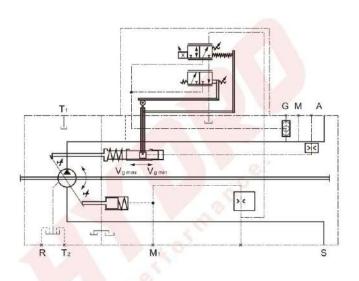
- at operating pressure and external control pressure < 3 MPa: Vg max
- at operating pressure or external control pressure > 3 MPa:Vg min

#### Characteristic LRU1/2

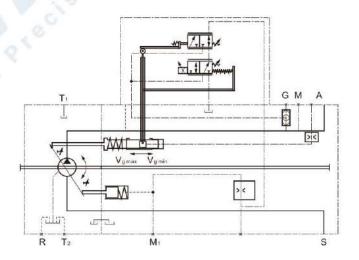


#### Circuit diagram LRU1/2

Size:40...145



Size:190...260





#### DR - Pressure Control

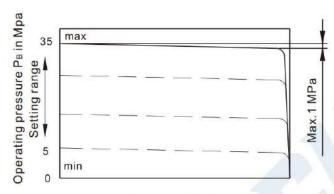
#### DR Pressure control

The pressure control keeps the pressure in a hydraulic system constant within its control range even under varying flow conditions. The variable pump only moves as much hydraulic fluid as is required by the actuators. If the operating pressure exceeds the setpoint set at the integral pressure control valve, the pump displacement is automatically swivelled back until the pressure deviation is corrected.

Starting position in depressurized state:  $V_{g\,max}$ 

Setting range from 5 to 35 Mpa.

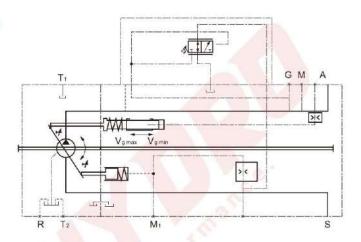
#### Characteristic DR

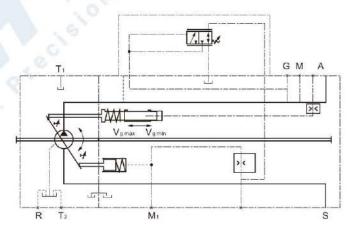


Flow qv in L/min -----

#### Circuit diagram DR

Size:40...145







#### DR - Pressure Control

#### DRS Pressure control with load sensing

The load sensing control is a flow control option that operates as a function of the load pressure to regulate the pump displacement to match the actuator flow requirement.

The flow depends here on the cross section of the external sensing orifice (1) fitted between the pump outlet and the actuator. The flow is independent of the load pressure below the pressure cut-off setting and within the control range of the pump.

The sensing orifice is usually a separately arranged load sensing directional valve (control block). The position of the directional valve piston determines the opening cross section of the sensing orifice and thus the flow of the pump.

The load sensing control compares pressure before and after the sensing orifice and maintains the pressure drop across the orifice (differential pressure  $\triangle P$ ) and with it the pump flow constant.

If the differential pressure  $\triangle P$  increases at sensing orifice, the pump is swivelled back (towards  $V_{g\,min}$ ),and,if the differential pressure  $\triangle P$  decreases,the pump is swivelled out (towards  $V_{g\,max}$ ) until the pressure drop across the sensing orifice in the valve is restored.

△ Porifice = Ppump - Pactuator

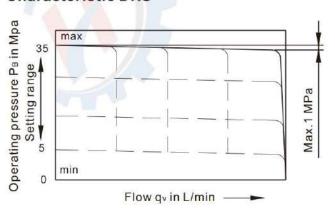
The setting range for  $\triangle P$  is between 1.4MPa and 2.5MPa.

The standard differential pressure setting is 1.8MPa. (Please state in clear text when ordering).

The stand-by pressure in zero stroke operation(sensing orifice plugged) is slightly above the  $\triangle P$  setting.

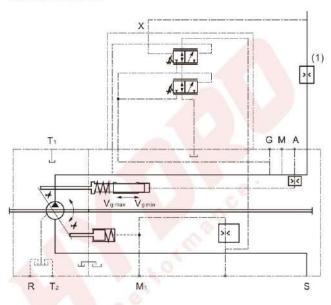
(1) The sensing orifice (control block) is not included in the pump supply.

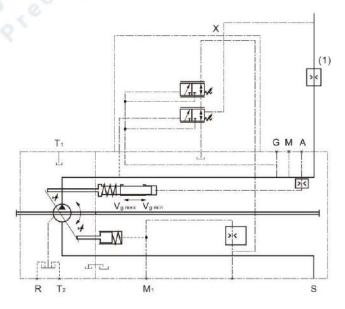
#### Characteristic DRS



#### Circuit diagram DRS

Size:40...145







#### EP - Electric Control With Proportional Solenoid

With the electric control with proportional solenoid, the pump displacement is adjusted proportionally to the solenoid current, resulting in a magnetic control force, acting directly onto the control spool that pilots the pump control piston.

Control from Vg min go Vg max

With increasing control current the pump swivels to a higher displacement.

Starting position without control signal(control current):

- at operating pressure and external control pressure  $< 3MPa: V_{g max}$
- at operating pressure and external control pressure
   3MPa: Vg min

A control pressure of 3 MPa is required to swivel the pump from its starting position  $V_{g\,max}$  to  $V_{g\,min}$ .

The required control pressure is taken either from the load pressure, or from the externally applied control pressure at port G.

To ensure the control even at low operating pressure < 3 MPa the port G must be supplied with an external control pressure of approx.3 MPa.

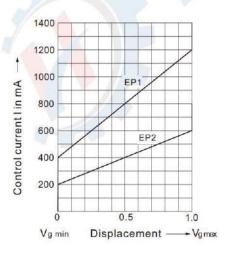
#### Note:

If no external control pressure is connected at G, the shuttle valve must be removed.

#### Note:

Install pump with EP control in the oil tank only when using mineral hydraulic oils and an oil temperature in the tank of max.80°C.

#### Characteristic EP1/2

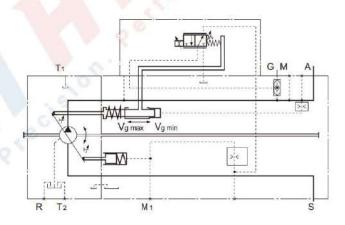


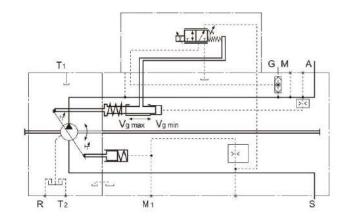
#### Technical data - solenoids

	Ep1	Ep2
Voltage	12V DC (±20%)	24V DC (±20%)
Control current		
Start of control at V <sub>gmin</sub>	400mA	200mA
End of control at V <sub>gmax</sub>	1200mA	600mA
Limiting current	1.54A	0.77A
Nominal resistance(at 20°C)	5.5Ω	22.7Ω
Dither frequency	100Hz	100Hz
Actuated time	100%	100%
Type of protection	IP6	55

#### Circuit diagram EP1/2

Size:40...145







#### EP - Electric Control With Proportional Solenoid

#### EP.D Electric control with pressure cut-off

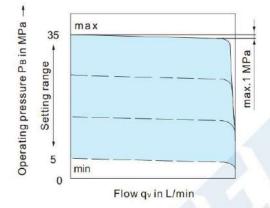
The pressure cut-off corresponds to a pressure control which adjusts the pump displacement back to Vg min when the pressure setting is reached.

This function overrides the EP control,i.e.the control current related displacement control is functional below the pressure setting.

The valve for the pressure cut-off is integrated in the control case and is set to a fixed specified pressure value at the factory.

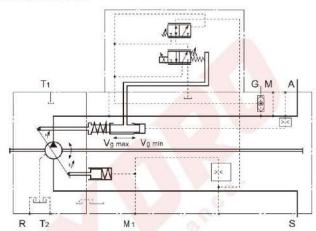
Setting range from 5 to 35 Mpa.

#### Pressure cut-off characteristic D

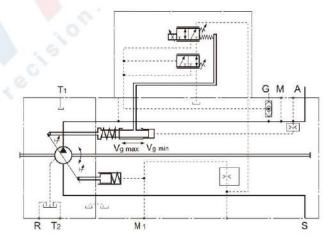


#### Circuit diagram EP.D

Size:40...145

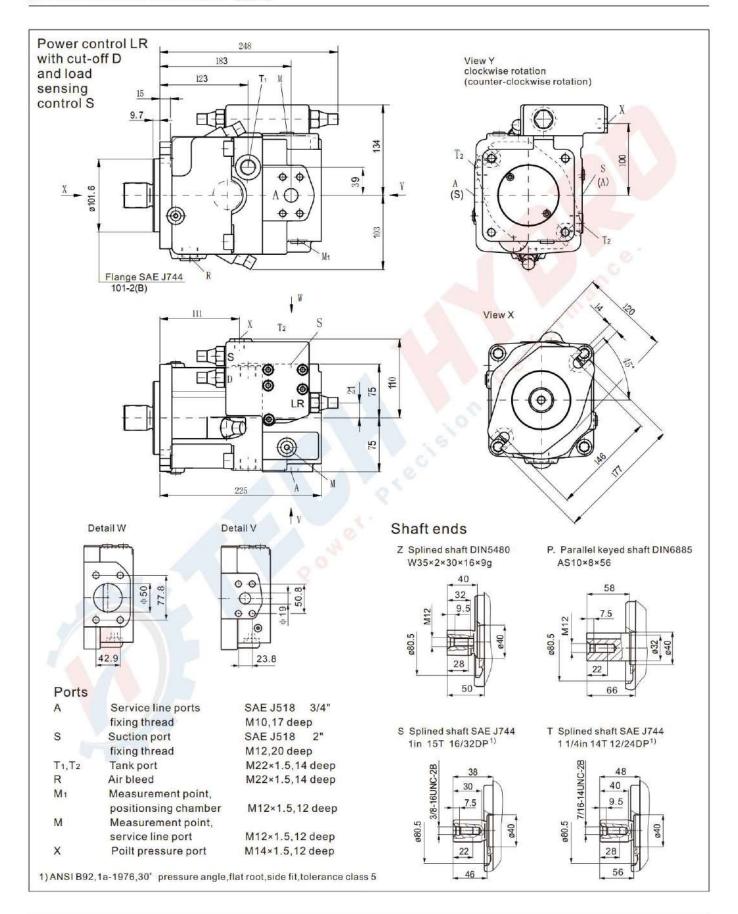


Size:190...260





#### Installation dimensions Size 40

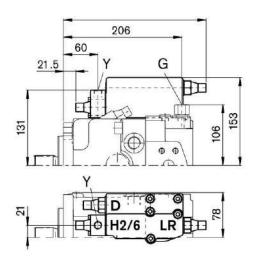






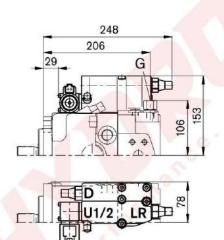
#### LRDH2/LRDH6:

Power control with pressure cut-off and hydraulic stroke limiter(positive characteristic)



#### LRDU1/LRDU2:

Power control with pressure cut-off and electric stroke limiter(positive characteristic)



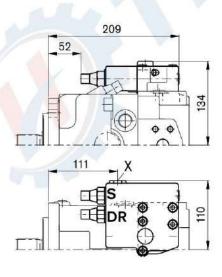
(

Poilt pressure port

M14×1.5,12 deep

#### DRS:

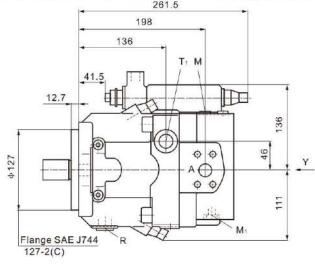
Pressure control with load sensing control



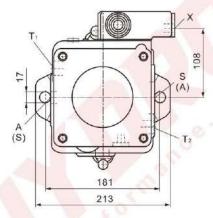


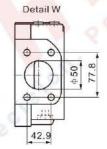
#### Installation dimensions Size 60

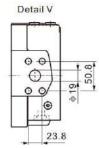
#### Power control LR with cut-off D and load sensing control S



View Y clockwise rotation (counter-clockwise rotation)

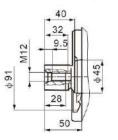


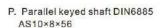


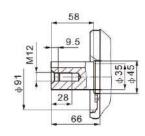


#### Shaft ends

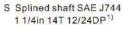
Z Splined shaft DIN5480 W35×2×30×16×9g

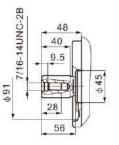




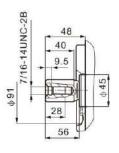




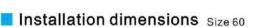




T Splined shaft SAE J744 1 3/8in 21T 16/32DP<sup>1)</sup>



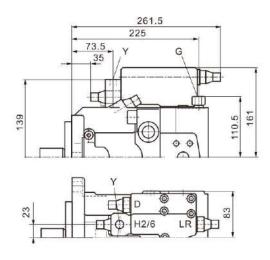
1) ANSI B92,1a-1976,30° pressure angle,flat root,side fit,tolerance class 5



# TECH HYDRO Power. Precision. Performance.

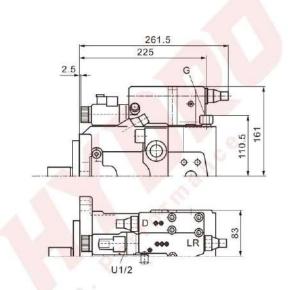
#### LRDH2/LRDH6:

Power control with pressure cut-off and hydraulic stroke limiter(positive characteristic)



LRDU1/LRDU2:

Power control with pressure cut-off and electric stroke limiter(positive characteristic)



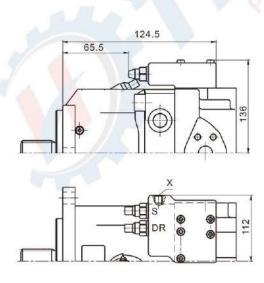
Poilt p

Poilt pressure port

M14×1.5,12 deep

#### DRS:

Pressure control with load sensing control



A11V(L)O...

20



#### Installation dimensions Size 75

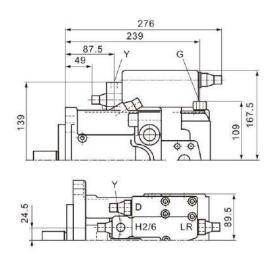
#### Power control LR with cut-off D and load sensing control S 215 View Y clockwise rotation 148 (counter-clockwise rotation) 12.7 142.5 0 Ф152.4 20 A (S) 0 0 0 0 0 Flange SAE J744 152-4(D) ф21 162 200 138.5 Detail W Detail V 19 0 0 24.5 88.5 27.8 Shaft ends 260 Z Splined shaft DIN5480 P Parallel keyed shaft DIN6885 W40×2×30×18×9g AS12×8×80 82 Ports Service line ports **SAE J518** 36 M12,17 deep fixing thread Suction port S **SAE J518** 2 1/2" fixing thread M12,17 deep $T_1, T_2$ Tank port M22×1.5,14 deep R Air bleed M22×1.5,14 deep S Splined shaft SAE J744 T Splined shaft SAE J744 Mi Measurement point, 1 1/4in 14T 12/24DP 1) 1 3/8in 21T 16/32DP 1) positionsing chamber M12×1.5,12 deep ф 96 7/16-14UNC-2B M Measurement point, service line port M12×1.5,12 deep 40 X Poilt pressure port M14×1.5,12 deep 9.5

1) ANSI B92,1a-1976,30° pressure angle, flat root, side fit, tolerance class 5



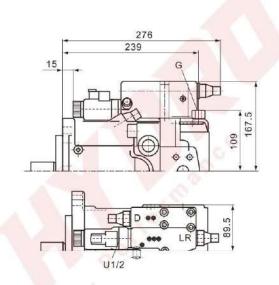
#### LRDH2/LRDH6:

Power control with pressure cut-off and hydraulic stroke limiter(positive characteristic)



LRDU1/LRDU2:

Power control with pressure cut-off and electric stroke limiter(positive characteristic)



Y Poilt pressure port
G Port for control pressure

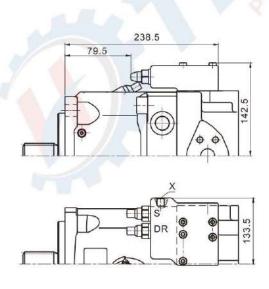
M14×1.5,12 deep

(controller)

M14×1.5,12 deep

#### DRS:

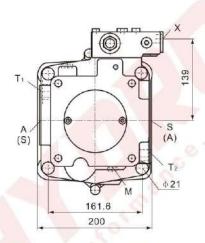
Pressure control with load sensing control





# Installation dimensions Size 95,115 Power control LR with cut-off D and load sensing control S 234 155 Ti M 12.7 157 0 Θ 20 **♦152.4** 0 0 0 125 Flange SAE J744 152-4(D) 150 20

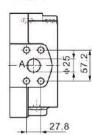
View Y clockwise rotation (counter-clockwise rotation)



Detail W

106.5

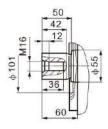
Detail V



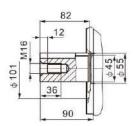
# 96 96 287

#### Shaft ends

Z Splined shaft DIN5480 W45×2×30×21×9g



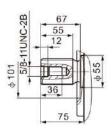
P Parallel keyed shaft DIN6885 AS14×9×80





Service line ports	SAE J518 1"
fixing thread	M12,17 deep
Suction port	SAE J518 3"
fixing thread	M12,17 deep
Tank port	M26×1.5,16 deep
Air bleed	M26×1.5,16 deep
Measurement point,	
positionsing chamber	M12×1.5,12 deep
Measurement point,	Control of the state of the sta
service line port	M12×1.5,12 deep
Poilt pressure port	M14×1.5,12 deep
	fixing thread Suction port fixing thread Tank port Air bleed Measurement point, positionsing chamber Measurement point, service line port

S Splined shaft SAE J744 1 3/4in 13T 8/16DP 1)

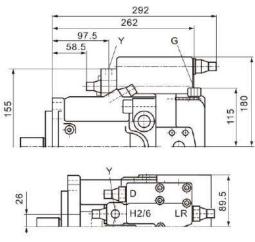


1) ANSI B92,1a-1976,30° pressure angle, flat root, side fit, tolerance class 5



#### LRDH2/LRDH6:

Power control with pressure cut-off and hydraulic stroke limiter(positive characteristic)



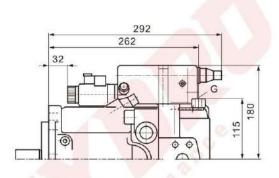
Y Poilt pressure port Port for control pressure (controller)

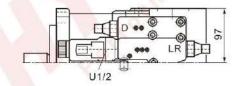
M14×1.5,12 deep

M14×1.5,12 deep

#### LRDU1/LRDU2:

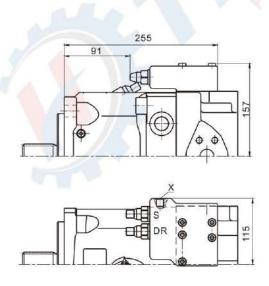
Power control with pressure cut-off and electric stroke limiter(positive characteristic)





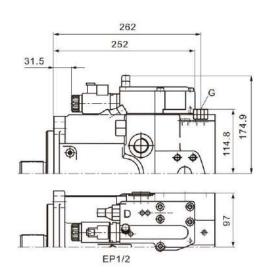
#### DRS:

Pressure control with load sensing control

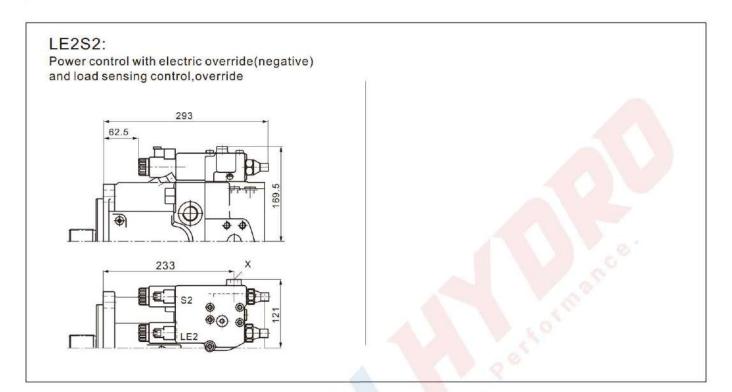


#### EP1D/EP2D:

Electric control with proportional solenoid and pressure cut-off



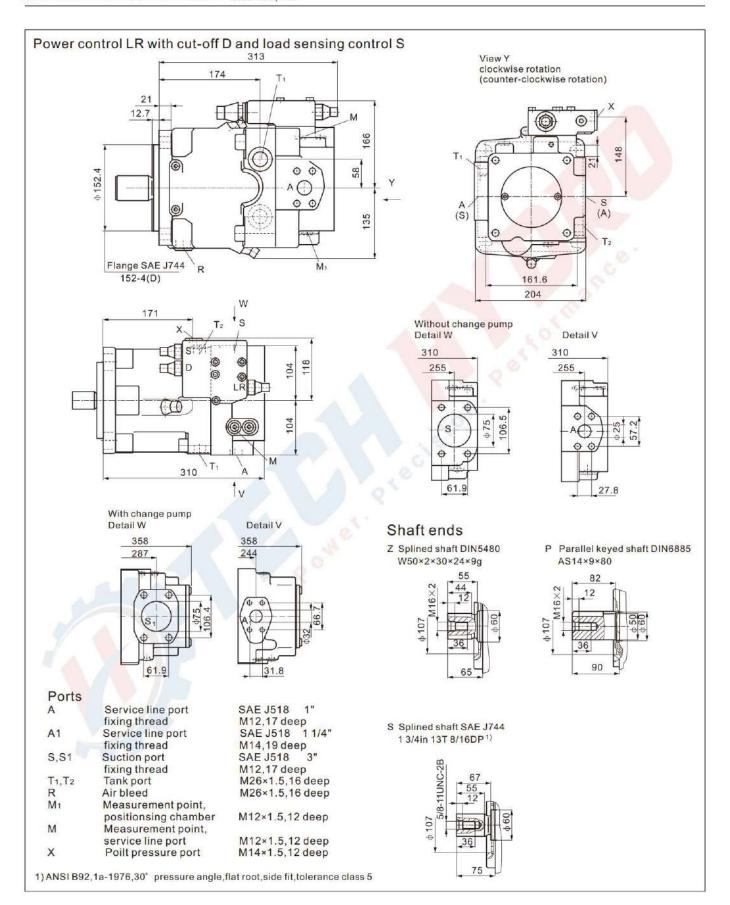
## ■ Installation dimensions Size 95,115







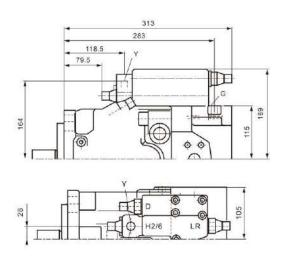
#### Installation dimensions Size 130,145





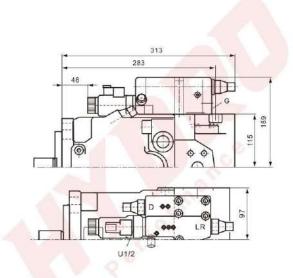
#### LRDH2/LRDH6:

Power control with pressure cut-off and hydraulic stroke limiter(positive characteristic)



LRDU1/LRDU2:

Power control with pressure cut-off and electric stroke limiter(positive characteristic)



Y Poilt pressure port
G Port for control pressure

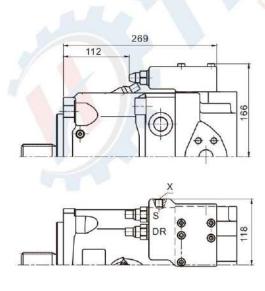
M14×1.5,12 deep

(controller)

M14×1.5,12 deep

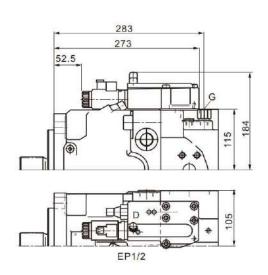
#### DRS:

Pressure control with load sensing control



#### EP1D/EP2D:

Electric control with proportional solenoid and pressure cut-off



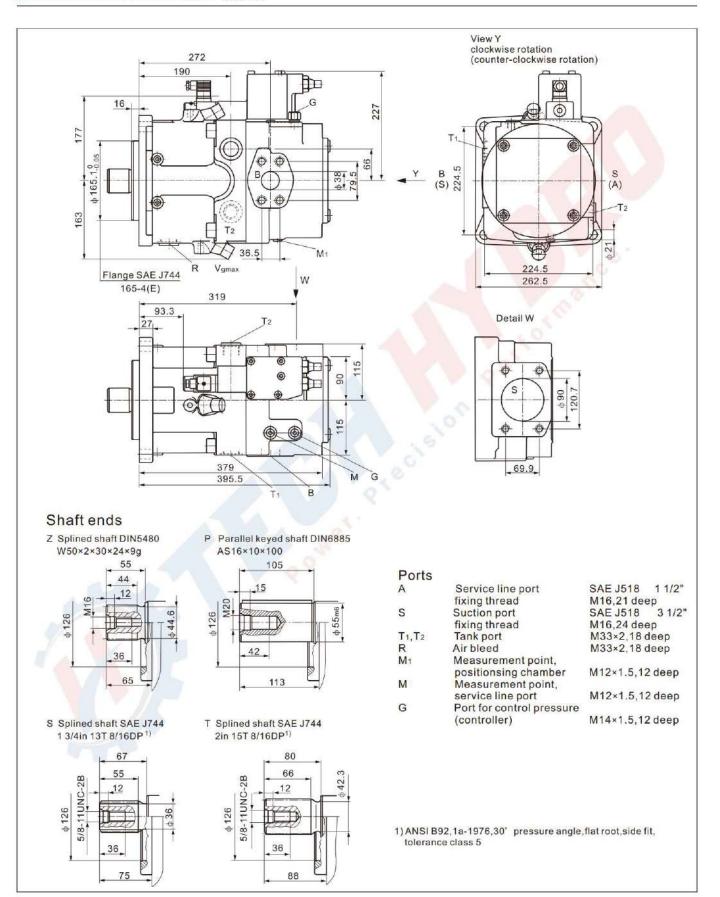
## ■ Installation dimensions Size 130,145

# LE2S2: Power control with electric override(negative) and load sensing control, override





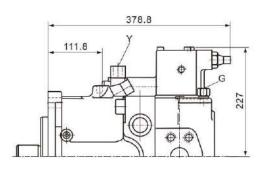
#### Installation dimensions Size 190

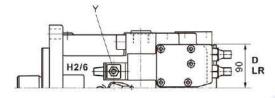




#### LRDH2/LRDH6:

Power control with pressure cut-off and hydraulic stroke limiter(positive characteristic)



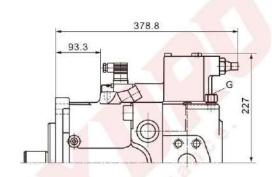


Y Poilt pressure port

M14×1.5,12 deep

#### LRDU1/LRDU2:

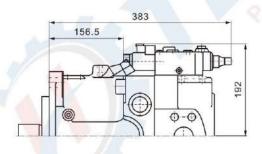
Power control with pressure cut-off and electric stroke limiter(positive characteristic)

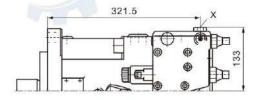




#### LE2S2:

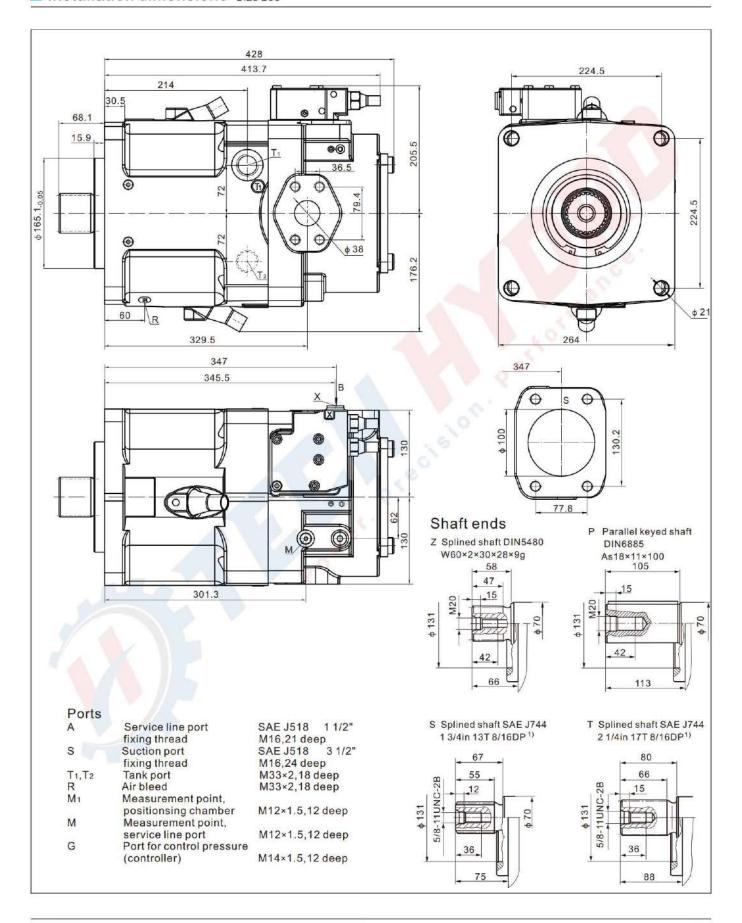
Power control with electric override(negative) and load sensing control, override







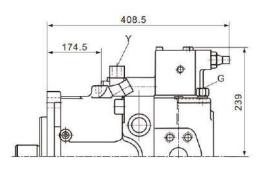
#### Installation dimensions Size 260

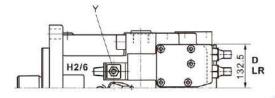




#### LRDH2/LRDH6:

Power control with pressure cut-off and hydraulic stroke limiter(positive characteristic)



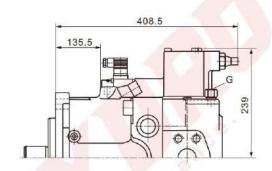


Y Poilt pressure port

M14×1.5,12 deep

#### LRDU1/LRDU2:

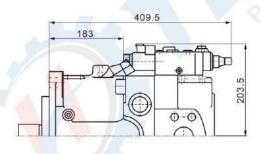
Power control with pressure cut-off and electric stroke limiter(positive characteristic)

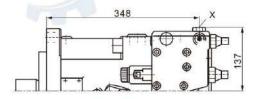




#### LE2S2:

Power control with electric override(negative) and load sensing control, override

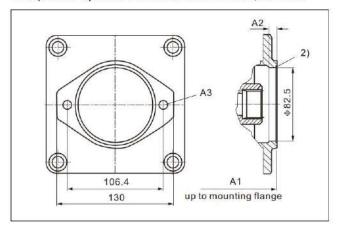






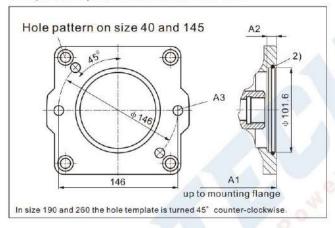
#### Through Drive Dimensions

Flange SAE J744-82-2(A)
Coupler for splined shaft acc. to ANSI B92, 1a-1976

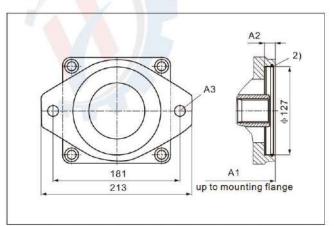


Flange SAE J744-101-2(B)
Coupler for splined shaft acc. to ANSI B92, 1a-1976

Coupler for splined shaft acc.to DIN 5480



Flange SAE J744-127-2(C)
Coupler for splined shaft acc. to ANSI B92,1a-1976
Coupler for splined shaft acc. to DIN 5480



NOTE: The mounting flange may be turned through 90°. Standard position as illustrated. Please state in clear text if required.

5/8in 9T 16/32DP<sup>1)</sup> (SAE J744-16-4(A)) K01 3/4in 11T 16/32DP<sup>1)</sup> (SAE J744-19-4(A-B)) K52

A1		A2	A3
K01	K52		
240	240	8	M10;15 deep
257	257	84.0	M10;15 deep
275	275	2	M10;15 deep
306	306	/- >	M10;12.5 deep
329	329	4	M10;12.5 deep
363	363	<b>25</b> .0	M10;12.5 deep
394	394	-	M10;13 deep
427.3	427.3	1-1	M10;13 deep
	K01 240 257 275 306 329 363 394	K01 K52 240 240 257 257 275 275 306 306 329 329 363 363 394 394	K01     K52       240     240     8       257     257     -       275     275     -       306     306     -       329     329     -       363     363     -       394     394     -

\*) Version with charge pump

7/8in 13T 16/32DP<sup>1)</sup> (SAE J744-22-4(B)) K02 1in 15T 16/32DP<sup>1)</sup> (SAE J744-25-4(B-B)) K04

W35×2×30×16×9g

K79

	A1			A2	A3
Size	K02	K04	K79		
40	244	244		10	M12;19 deep
60	261	261	261	10	M12;19 deep
75	279	279		10	M12;19 deep
95/115	303	303	303	10	M12;16 deep
130/145	326	326	326	10	M12;16 deep
130/145*	360	360	360	10	M12;16 deep
190*	404	404	394	u	M12;15 deep
260*	437.5	437.5	437.5	ě	M12;15 deep

\*) Version with charge pump

1 1/4in 14T 12/24DP¹) (SAE J744-32-4(C)) K07 1 1/2in 17T 12/24DP¹) (SAE J744-38-4(C-C)) K24 W30×2×30×14×9g K80

W30×2×30×14×9g W35×2×30×16×9g

	A1				A2	A3
Size	K07	K24	K80	K61		
60	272	-	265	265	13	M16,20 deep
75	290	-	283	283	13	M16,20 deep
95/115	318	318	318	318	13	M16,20 deep
130/145	330	330	330	330	13	M16,20 deep
130/145*	364	364	364	364	13	M16,20 deep
190*	400	400	400	400	13	M16,19 deep

\*) Version with charge pump

1) 30° pressure angle, flat root, side fit, tolerance class 5

2) O-ring included in the delivery contents

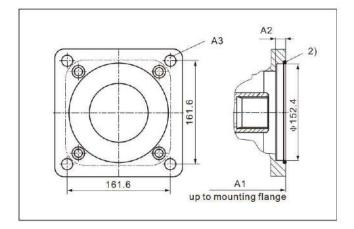
K61



#### Through Drive Dimensions

Flange SAE J744-152-4(A) Coupler for splined shaft acc. to ANSI B92, 1a-1976

Coupler for splined shaft acc. to DIN 5480



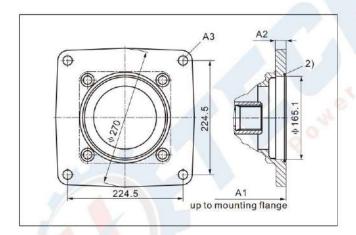
(SAE J744-32-4(C))	K86
(SAE J744-44-4(D))	K17
	K81
	K82
	K83
	(SAE J744-32-4(C)) (SAE J744-44-4(D))

	A1					A2	А3
Size	K86	K17	K81	K82	K83		
75	290	-	290	-	-	13	M20,28 deep
95/115	317	(4)	317	317	-	30	M20,25 deep
130/145	340	350	340	340	340	30	M20,25 deep
130/145*	374	384	374	374	374	30	M20,25 deep
190*	424	424	424	424	424	13	M20,22 deep
260*	459	459	459	459	459	13	M20,22 deep

<sup>\*)</sup> Version with charge pump

Flange SAE J744-165-4(E) Coupler for splined shaft acc. to ANSI B92, 1a-1976

Coupler for splined shaft acc. to DIN 5480



1 3/4in 13T 8/16DP <sup>1)</sup> (SAE J744-32-4(C))	K72
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W50×2×30×24×9g	K84
W60×2×30×28×9g	K67

		A1		A2	А3
Size	K72	K84	K67		
190*	409	409	-	19	M20;20 deep
260*	459	442.5	442.5	19	M20;20 deep

<sup>\*)</sup> Version with charge pump

The mounting flange may be turned through 90°. Standard position as illustrated. Please state in clear text if required. 1) 30° pressure angle, flat root, side fit, tolerance class 5. 2)O-ring included in the delivery contrnts.



#### Installation Notes

#### General

During commissioning and operation, the axial piston unit must be filled with hydraulic fluid and air bled. This is also to be observed following a relatively long standstill as the system may empty via the hyddraulic lines.

The case drain in the case interior must be directed to the tank via the highest tank port(T1,T2). The minimum suction pressure at port S must not fall below 0.08 Mpa absolute (without charge pump) or 0.06MPa (with charge pump).

In all operational conditions, the suction line and case drain line must flow into the tank below the minimum fluid level.

#### Below-tank installation(standard)

Pump below the minimum fluid level of the tank.

- Any installation position
- Mounting position "shaft up"

It must be ensured that the pump casing is completely filled with oil during commissioning. If air bubbles appear at the bearing, it will damage the axial plunger bengbu.

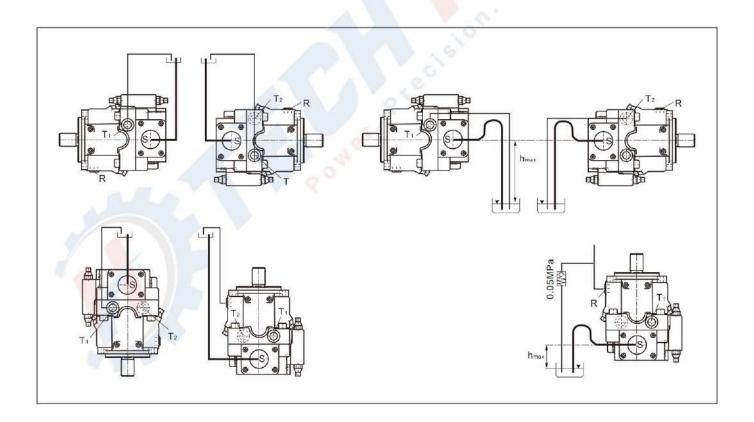
#### Above-tank installation

Pump above the minimum fluid level of the tank. Observe the maximum permissible scution height H<sub>s max</sub>=800 mm.

The version A11VLO(with charge pump) is not designed for installation above the tank.

Recommendation for installation shaft up:A check valve in the case drain line(opening pressure 0.05MPa) can prevent the case interior from draining.

For control options with pressure control, displacement limiters, HD and EP control, the minimum displacement setting must be V<sub>g</sub>≥5% V<sub>g max</sub>.





# FOR MORE INFORMATION PLEASE CONTACT US

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