

# A10VG Series Axial piston variable pump

#### Product show and brief introduction

#### Colsed circuits

Series 10 Sizes 45 Nominal pressure 30MPa Maxmum pressure 35MPa



#### Features

- Integrated boost pump for bosst and pilot oil supply
- Flow direction changes when the swashplate is moved through the neutral position
- High-pressure relief valves with integrated boost function
- Boost-pressure relief valve
- Optional with pressure cut-off
- Swashplate design



#### Model Code

A10V	G	45	EP4	D	M.	/10	R	-N	S	С	10	F	01	3	S	P.
Axial piston unit	Operating mode	Size	Contro			Series	Driection of rotation	Seals		Mounting flange		Boost pump	Inrough	High- pressure relief valve		Connector for solenoids
A10V: swash- plate design, variable	G: pump; closed circuit	45	Coo	without pre- ssure cut- off D: with pre- ssure	No code: without mechanical troke limiter M: mechanical stroke limiter, externally adjustable	40	(Viewed on drive shaft) R: clockwise L: counter-	FKM (fluorcao-	below	2 -hole F: SAE J744 2+4-hole	and B, same side right,	See below	See below	See below	See below	DEUTSCH connector molded, 2-pin

# Control unit

	Size	45	
Proportional control nydraulic	pilot-pressure relatied, with inlet filtration in P and X <sub>1</sub> /X <sub>2</sub>	V	HD3
	mechanical servo	V	HW
Proportional control electric	with proportional solenoid with inlet filtration in P and X <sub>1</sub> /X <sub>2</sub> U=12V	V	EP3
	U=24V	V	EP4
Two-point control,	with switching solenoid U=24V	V	EZ1
Sissino	U=24V	V	EZ2

# Drive shafts

	Size 45	
Splined shaft ANSI B92.a-1976	for single pump	S
ANSI B92.8-1970	for combination pump	Т

# Boost pump

Size	45	
Without integrated boost pump without through drive	~	N
with through drive	V	K
Integrated boost pump with and without through drive	~	F



# Through drive

ange SAE J744 Hub for splined shaft		45	
Without through drive, only for version N and F		✓	00
82-2(A)	5/8" 9T 16/32DP	✓	01
101-2(B)	7/8" 13T 16/32DP	V	02
	1" 15T 16/32DP	V	04

# High-pressure relief valve

	Setting range		45	
High-pressure relief valve direct operated, fixed setting	2532MPa	without bypass	- V	3
		with bypass	~	5
	1025MPa	without bypass	V	4
		with bypass	V	6

# Filtration boost circuit/external boost pressure supply

	45	
Filtration in the boost pump suction line	✓	s
Filtration in the boost pump pressusre line Ports for external boost circuit filtration(Fe and G(Fa))	√	D
External boost pressure supply(version without integrated boost pump -N00,K)	√	Е



#### Technical Data

#### Hydraulic fluid

The A4VG variable displacement pump is suitable for use with mineral oil

#### Viscosity range

We recommend that a viscosity (at operating temperature) for optimum efficiendy and service life purposes of

V<sub>ent</sub> = optimum viscosity16...36mm<sup>2</sup>/s

Be chosen, taken the tank temperature (closed circuit) into account.

#### Limits of viscosity range

The following values apply in extreme cases:

 $Vmin = 5 mm^2/s$ 

short term(t < 3 min)at max.permitted temperature tmax=115°C

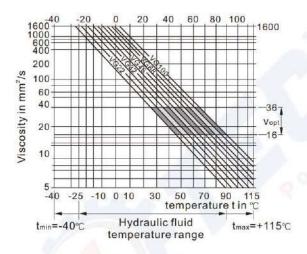
 $Vmax = 1600 mm^2/s$ 

short term(t < 3 min) with cold start(P < 3MPa,

n≤1000rpm tmin=-40°C)

Note that the maximun hydraulic fluid temperature must not be exceeded locally either (e.g.bearing area). The temperature in the bearing area is-depending on pressure and speed-up to 12K higher than the average case drain temperature.

#### Setlection diagram



#### Details regarding the choice of hydraulic fluid

The correct selection of hydraulic fluid requires knowledge of the operating temperature in relation to the ambient temperature, in an open circuit the tank temperature.

The hydraulic fliuid should be selected so that within the operating temperature range, the operating viscosity lies within the optimun range (Vopt) (see shaded section of the selection diagram). We recommend that the highest possible viscosity range should be chosen in each case.

Example: At an ambient temperature of X°C an operating temperature of 60°C is set in the circuit. In the optimun operating viscosity range(Vopt; shaded area) this corresponds to the viscosity classes VG 46 or VG68; to be selected: VG 68.

Please note: The leakage fluid temperature, which is affected by pressure and rotational spaad, is always higher than the tank temperature. At no point in the system may the temperature be higher than 115℃.

#### Filtartion

Finer filtration improves the cleanliness level of the hydraulic fluid ,witch increases the service life of the axial piston unit.

A cleanliness level of at least 20/18/15 is to be maintained according to ISO 4406.

At a hydraulic fluid visconsity of less than 10 mm2/s(e.g.due to high temperatures during short-term operation), a cleanlinesss level of at least 19/17/14 according to ISO 4406 is required.

#### Operational pressure range

Variable pump(with external oil supply.E) With control EP, HW and HD Charge pressure(at n=2000rpm)Psp =1.8MPa With control DG Charge pressure(at n=2000rpm)Psp =2.5MPa Charge pump Suction pressure Ps min(V≤30mm2/s)

#### Output:

Variable pump

Pressure at nort A or B

recodere at port re or b	
Nominal pressure PN	30MPa
Peak pressure Pmax	35MPa
Total pressure (pressure A+pressure B) Pmax	60MPa
Charge pump	
Peak pressure Psp max	4MPa

#### Shaft seal

#### Permissible pressure loading

The service life of the shaft seal is influenced by the rotational speed of the axial piston unit and the leakage pressure in the housing (case pressure). Momentary (t < 0.1s) pressure peaks of up to 1MPa are allowed. Case pressure of a continuous 0.2MPa maximum are permitted to be able to utilize the entire speed range. Higher case pressure are permissible at lower rotational speeds.

The service life of the shaft seal decreases with increasing frequency of pressure peaks and increasing mean differential pressure. The case pressure must be equal to or higher than the ambient pressure.

#### Temperature range

The FKM shaft seal ring may be used for leakage temperature from -25°C to +115°C. For application cases below -25°C, an NBR shaft seal is required(permissible temperature range:-40°C to +90°C).



#### Technical Data

Size				45
Geometric displacement,per revolu	tion			
variable pump		Vg max	mL/r	46
boost pump (at P=2MPa)		Vg sp	mL/r	13,8
Rotational speed				
maximum at Vg max		nmax continuous	rpm	3300
limited maximum <sup>1)</sup>		Nmax limited	rpm	3550
intermittent maxium <sup>2)</sup>		Nmax interm	rpm	3800
minimum		nmin	rpm	500
Flow				
at nnom and Vg max		Qv max	L/min	152
Power 3)			1000	
at nnom and Vg max	△P=30MPa	Pmax	kW	75.9
Torque <sup>3)</sup>			1 10	
with at Vg max	△P=30MPa	Tmax	Nm	220
	△P=10MPa	T	Nm	73.2
Moment of inertia of the rotary grou	p	J	kgm	0.0033
Maximum angular acceleration <sup>4)</sup>			rad/s <sup>2</sup>	4000
Maximum speed change 4)	4	A Comment	rpm	14
Case volume		V	L	0.75
Weight(without through drive) appre	nx .	M	kg	27

<sup>1)</sup> Valid at half corner power(e.g.at Vg max and Pn/2)

# Determining the nominal value

Flow 
$$q_v = \frac{V_g \times n \times \eta_v}{1000}$$
 (L/min)

Torque 
$$T = \frac{V_g \times \triangle P}{20 \times \pi \times \eta_{mh}}$$
 (Nm)

Power 
$$P = \frac{2\pi \times T \times n}{60000} = \frac{q_v \times \triangle P}{600 \times n_v}$$
 (kW)

$$\eta_t = \text{Overall efficiency}(\eta_t = \eta_v, \eta_{mh})$$

<sup>2)</sup> Valid at  $\triangle P=7MPa$  to 15 MPa or  $\triangle P<30MPa$  and t<0.1s

<sup>3)</sup> without boost pump

<sup>4)</sup> the limit value is only valid for a single pump.

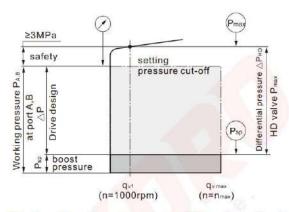


#### Hgih-pressure Relief Valves

#### Setting ranges

High-pressure relief valve, direct operated	Differential pressure setting △Php	
Setting range valve 3  \( \text{Php} = 25-32MPa \)	32 MPa	
	30 MPa	
	27 MPa	
Setting range valve 4 △PHD =10-25MPa	25 MPa	
	23 MPa	
	20 MPa	
	15 MPa	
	10 MPa	

#### Setting diagram



Note: the valve settings are made at n=1000 rpm and at Vg max(qv1),

Example:charge pressure 2 MPa, working pressure 29 Mpa working pressure PAB - Boost pressure PSP = Differential pressure △PHD 29 MPa - 2MPa = 27 MPa

#### Bypass function

A connection between the two high-pressure passages A and B can be established using the bypass function(e.g.for machine towing).

## Pressure cut-off,D

The pressure cut-off is a pressure control which, after reaching the set pressure, adjusts the displacement of the pump back to  $V_{\text{gmin}}$ .

This valve prevents the operation of the high-pressure relief valves when accelerating or decelerating.

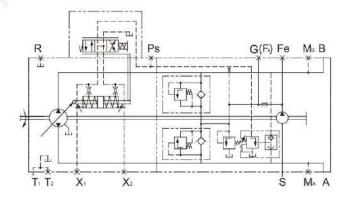
The high-pressure relief valves protect against the pressure peaks which occur during fast swiveling of the swashplate and limit the maximum pressure in the system.

The setting range of the pressure cut-off may be anywhere within the entire working pressure range. However, it must at least be set 3 Mpa lower than the setting value of the high-pressure relief valves.

Please state the setting value of the pressure cut-off in plain text when ordering.

# Circuit diagram with pressure cut-off

Example: Proportional control, hydraulic HW



# DG - Hydraulic control, direct operated

With the direct operated hydraulic control (DG), the output flow of the pump is controlled by a hydraulic control presssure, applied directly to the stroking piston through either port X1 and X2.

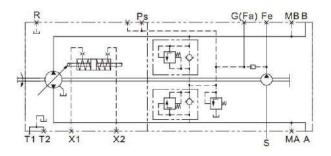
Flow direction is determined by which control pressure port is pressurized.

Pump displacement is infinitely variable and proportional to the applied control pressure, but is also influenced by system pressure, but is also influenced by system pressure and pump drive speed.

In order to use the optional built-in pressure cut-off, port PS must be used as source of the control pressure X1,X2.

Rotation direction-control-flow direction relationship see HD control on page 7 (control pressure X1,X2).

#### Circuit diagram



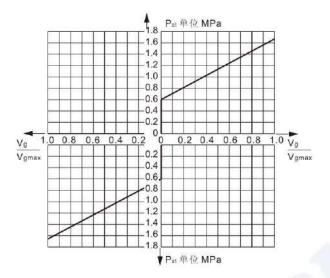


#### HD-Proportional control, hydraulic, pilot-pressure related

The output flow of the pump is infinitely variable between o and 100%, proportional to the difference in pilot pressure applied to the two pilot signal ports (Y1 and Y2).

The pilot signal, coming from an external source, is a pressure signal. Flow is negligible, as the pilot signal acts only on the control spool of the control valve.

This control spool then directs control oil into and out of the stroking cylinder to adjust pump displacement as required. A feedback lever connected to the stroking piston maintains the pump flow for any given pilot signal within the control range.



V<sub>g</sub> Displacement

Vg max Maximum displacement

Pilot pressure Pst=0.6-1.67MPa for Ports Y1, Y2

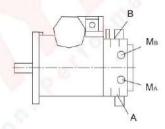
Start of control 0.6MPa (at Vg 0) End of control 1.67MPa (at Vg max)

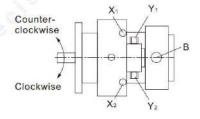
#### Notice:

In the neutral position, the HD control module must be unloaded to reservoir via the external pilot control device.

#### Correlation of direction of rotation, control and flow direction

		Pilot signal	Control pressure	Flow direction	Working pressure
ion	wise	<b>Y</b> 1	X1	A to B	Мв
Direction of rotation	Clockwise	<b>Y</b> 2	X2	B to A	MA
ction	ter- wise	<b>Y</b> 1	X1	B to A	MA
Dire	Counter- clockwise	<b>Y</b> 2	X2	A to B	Мв





# Circuit diagram HD3

# B MILIXIM PS G(Fa) Fe MBB TI T2 X1 X2 S MA A

#### Notice

The spring in the center of the pilot control is not a safety device.

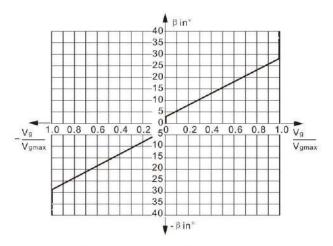
Due to contamination in the controls, such as contamination in the hydraulic oil, wear particles, and particles outside the system, the spool can become stuck in any position. In this case, the pump flow is no longer following the machine operator's command input.

- -Ensures that the emergency stop function can instantly bring the motion of the driven machine to a safe level (eg stop)



# HW-Proportional control, hydraulic, mechanical servo

The output flow of the pump is infinitely variable between o and 100%, proportional to the swivel angle of the control lever. A feedback lever connected to the stroking piston maintains the pump flow for any given position of the control lever.



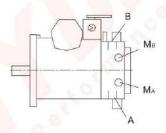
The swing angle of the lever when swinging  $\beta$ : Start of control  $\beta = \pm 3^{\circ}$  (at  $V_{g\,0}$ )

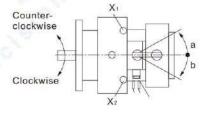
End of control  $\beta = \pm 29^{\circ}$  (at  $V_{g max}$ ) Rotational limiter control  $\beta = \pm 40^{\circ}$ 

The maximum required torque at control lever is 170 Ncm.To prevent damage to the HW control module, a positive mechanical stop of 38°  $\pm 1$  must be provided for the HW control lever on the customer side.

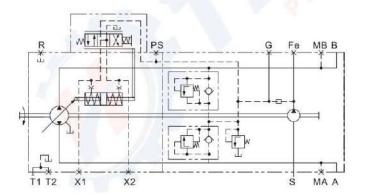
#### Correlation of direction of rotation, control and flow direction

		Lever direction	Control pressure	Flow direction	Working pressure
ion	wise	a	X2	B to A	Ма
Direction of rotation	Clockwise	b	X1	A to B	Мв
ction	iter- wise	а	X2	A to B	Мв
Dire	Counter- clockwise	b	X1	B to A	Ма





# Circuit diagram HW

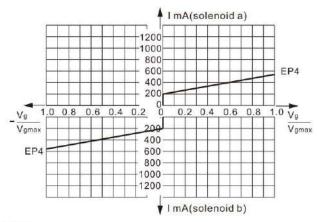




#### EP-Proportional control, electric

The output flow of the pump is infinitely variable between o and 100%, proportional to the electric current supplied to solenoid a or b.

The electrical energy is converted into a force acting on the control spool. This control spool then directs control oil into and out of the stroking cylinder to adjust pump displacement as required. A feedback lever connected to the stroking piston maintains the pump flow for any given current within the control range.



#### Notice:

The proportional solenoid do not have manual override. Proportional solenoid with manual override and spring return are available on request.

Technical data, proportional solenoid	EP3	EP4
Voltage	12V DC(±20%)	24V DC(±20%)
Control current		
Start of control at V <sub>g</sub> 0	400mA	200mA
End of control at Vg max	1200mA	600mA
Current limit	1.54A	0.77A
Nominal resistance(at 20°C	5.5Ω	22.7Ω
Frequency	100Hz	100Hz
Duty cycle	100%	100%
Type of protection	Ip6	35

#### Notice

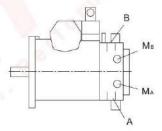
The spring in the center of the pilot control is not a safety device.

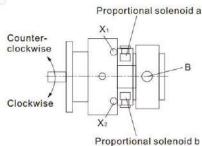
Due to contamination in the controls, such as contamination in the hydraulic oil, wear particles, and particles outside the system, the spool can become stuck in any position. In this case, the pump flow is no longer following the machine operator's command input.

- -Ensures that the emergency stop function can instantly bring the motion of the driven machine to a safe level (eg stop)

#### Correlation of direction of rotation, control and flow direction

		Actuation of proportional solenoid	Control pressure	Flow direction	Working pressure
ion	Clockwise	а	X1	A to B	Мв
of rotat	Clock	b	X2	B to A	Ма
Direction of rotation	ter- wise	а	X1	B to A	MA
Dire	Counter- clockwise	b	X2	A to B	Мв







## EZ-Two-point control, electric

By actuating either switching solenoid a or b, internal control pressure is applied directly to the stroking piston and the pump swivels to maximum displacement.

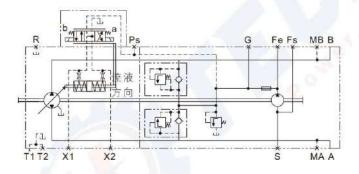
The EZ control enables pump flow to be switched between  $V_g$ = 0 and  $V_g$  max.

Flow direction is determined by which solenoid is energized.

Technical data, switching solenoid	EZ1	EZ2
Voltage	12V DC(±20%)	24V DC(±20%)
Neutral position V <sub>g</sub> =0	de-energized	de-energized
Position V <sub>g max</sub>	current switched on	current switched on
Nominal resistance(at 20°C	$5.5\Omega$	$22.7\Omega$
Nominal power	26.2W	26.5W
Minimum required active current	1.32A	0.67A
Duty cycle	100%	100%
Type of protection	IP6	35

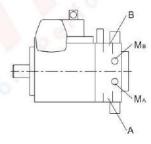
Standard: switch electromagnet without manual emergency operation function. Manual emergency operation via spring return is available on request.

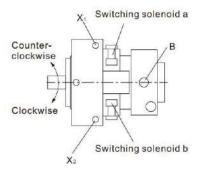
#### Circuit diagram EZ



#### Correlation of direction of rotation, control and flow direction

		Actuation of proportional solenoid	Control pressure	Flow direction	Working pressure
ion	wise	а	X2	B to A	MA
frotat	Clockwise	b	Χı	A to B	Мв
Direction of rotation	ter- wise	a	X2	A to B	Мв
Dire	Counter- clockwise	b	<b>X</b> 1	B to A	Ма

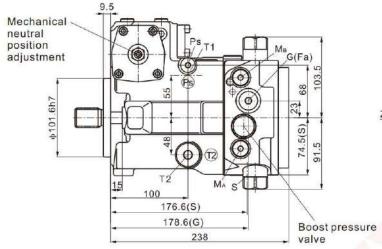


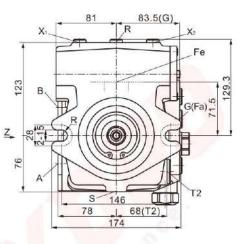


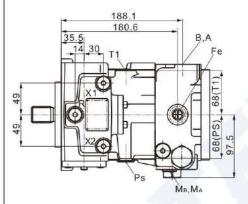


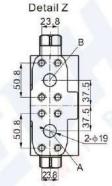
#### Installation dimensions

#### Without control valve









# Ports A,B

S T<sub>1</sub>  $T_2$ Ма,Мв R

X1, X2 G(Fa)

Ps Fe

Working port Fastening thread 3/4 in Suction port Drain port Drain port Measuring port

presssure A,B Air bleed port Control pressure port

(upstream of orifice) Boost pressure port inlet

Pilot pressure port Boost pressure port outlet M18×1.5;12 deep

M10;17 deep M33×2;15 deep M22×1.5;15 deep M22×1.5;15 deep

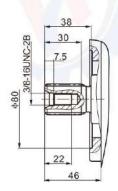
M12×1.5;12 deep M12×1.5;15 deep

M12×1.5;12 deep M18×1.5;12 deep

M14×1.5;12 deep

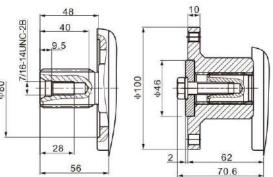
#### Shafts

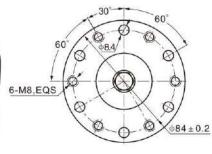
S spline shaft SAE J744 1 in 15T 16/32DP





L spline shaft SAE J744 with connecting flange

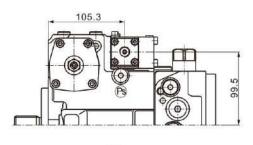


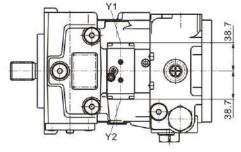




#### Installation dimensions

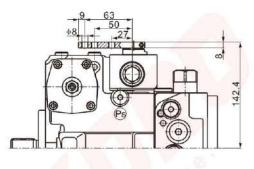
# HD-Proportional control, hydraulic, pilot-pressure related

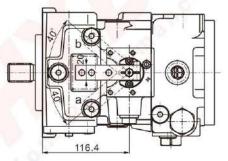




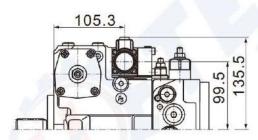
Y<sub>1</sub>,Y<sub>2</sub> Pilot pressure port outlet M14×1.5;12 deep

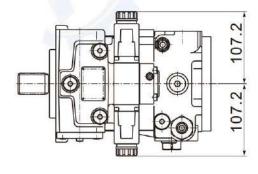
# HW-Proportional control, hydraulic, mechanical servo



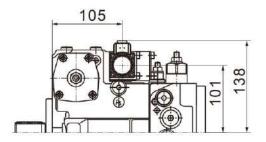


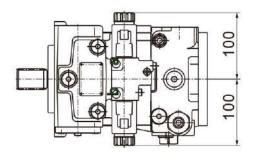
# EP-Proportional control, electric





# EZ-Two point control, electric

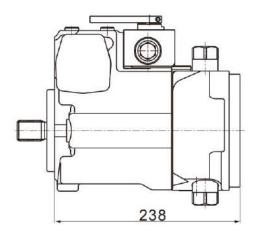






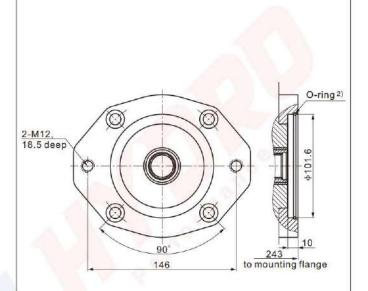
# Installation dimensions, through drive

N00-without boost pump F00-with boost pump

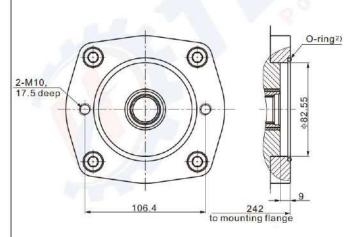


Flange SAE J744-82-2(A)
Coupler for splined shaft acc. to ANSI B92, 1a-1976

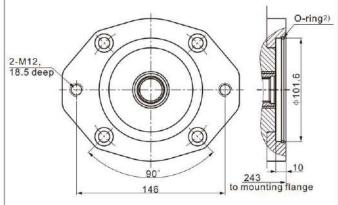
F02/K02 Flange SAE J744 Spline shaft sleeve to ANSI B92.1 7/8in 13T 16/32DP<sup>1)</sup>



F01/K01 Flange SAE J744 Spline shaft sleeve to ANSI B92.1 5/8in 9T 16/32DP1)



F04/K04 Flange SAE J744 Spline shaft sleeve to ANSI B92.1 1in 15T 16/32DP1)



- $1)\ Involute\ spline\ according\ to\ ANSI\ B92.1a, 30°\ pressure\ angle, flat\ root, side\ fit, tolerance\ class\ 5$
- 2) O-ring included in the scope of delivery

Note: please state in plain text whether the 2-hole horizontal or the 2-hole vertical version is used.



#### Installation instructions

#### General

The axial piston unit must be filled with hydraulic fluid and air bled during commissioning and operation. This must also be observed following a longer standstill as the axial piston unit may empty via the hydraulic lines.

Particularly in the installation position "drive shaft upwards", filling and air bleeding must carried out completely as there is, for example, a danger of dry running.

The leakage in the housing area must be directed to the reservoir via the highest drain port(T1, T2).

For combination pumps, the leakage must be drained off at each single pump.

If a shared drain line is used for several units, make sure that the respective case pressure in each unit is not exceeded. The shared drain line must be dimensioned to ensure that the maximum permissible case pressure of all connected units is not exceeded in any operating condition, particularly at cold start, If this is not possible, separate drain lines must be laid, if necessary.

To achieve favorable noise values, decouple all connecting lines using elastic elements and avoid above-reservoir installation.

Under all operating conditions, the suction line and drain line must flow into the reservoir below the minimum fluid level. The permissible suction height hs results from the total pressure loss; it must not however, be higher than hs max=800 mm.

The suction pressure at port S must also not fall below the minimum value of 0.8 bar absolut during operation(cold start 0.5 bar absolute).

#### Installation position

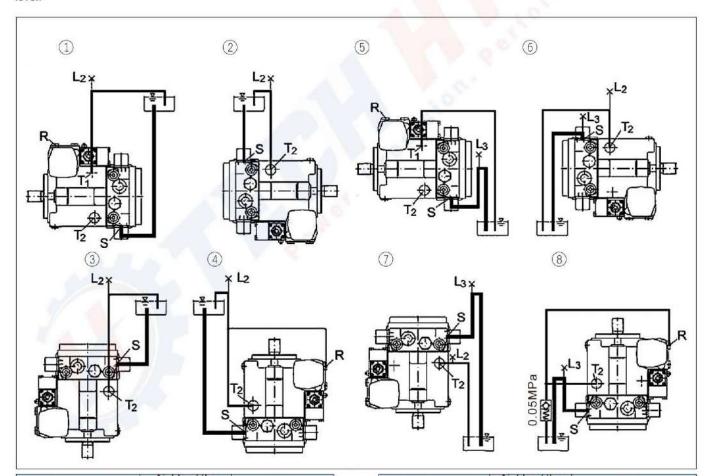
See the following example. Other installation positions available upon request.

#### Below-reservoir installation (standard)

Below-reservoir installation means that the axial piston unit is installed outside of the reservoir below the minimum fluid level.

#### Above-reservoir installation

Aboove-reservoir installation means that the axial piston unit is installed above the minimum fluid level of the reservoir, Observe the maximum permissible suction height h<sub>s max</sub>=800 mm. Recommendation for installation position 8 (drive shaft upward): A check valve in the drain line (cracking pressure 0.5bar) can prevent the housing area from draining.



Installation position	Air bleed the housing	Filling
1	R	S+T1(L2)
2	L2	$S+T_2(L_2)$
3	L <sub>2</sub>	S+T <sub>2</sub> (L <sub>2</sub> )
4	R+L2	S+T2(L2)

Installation position	Air bleed the housing	Filling
5	R	T1+(L3)
6	L2	S(L3)+T2(L2)
7	L2+L3	S(L3)+T2(L2)
8	R+L3	S(L <sub>3</sub> )+T <sub>2</sub>



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